

**Minimising wheel wear by
optimising the primary
suspension stiffness and
centre plate friction of
self-steering bogies**



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SAICE SYMPOSIUM

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PRESENTATION OVERVIEW

- **Introduction**
- **Bogie development**
- **Problem definition**
- **Running dynamics simulation models**
- **Running dynamics simulation results**
- **On-track tests**
- **Conclusions**

INTRODUCTION

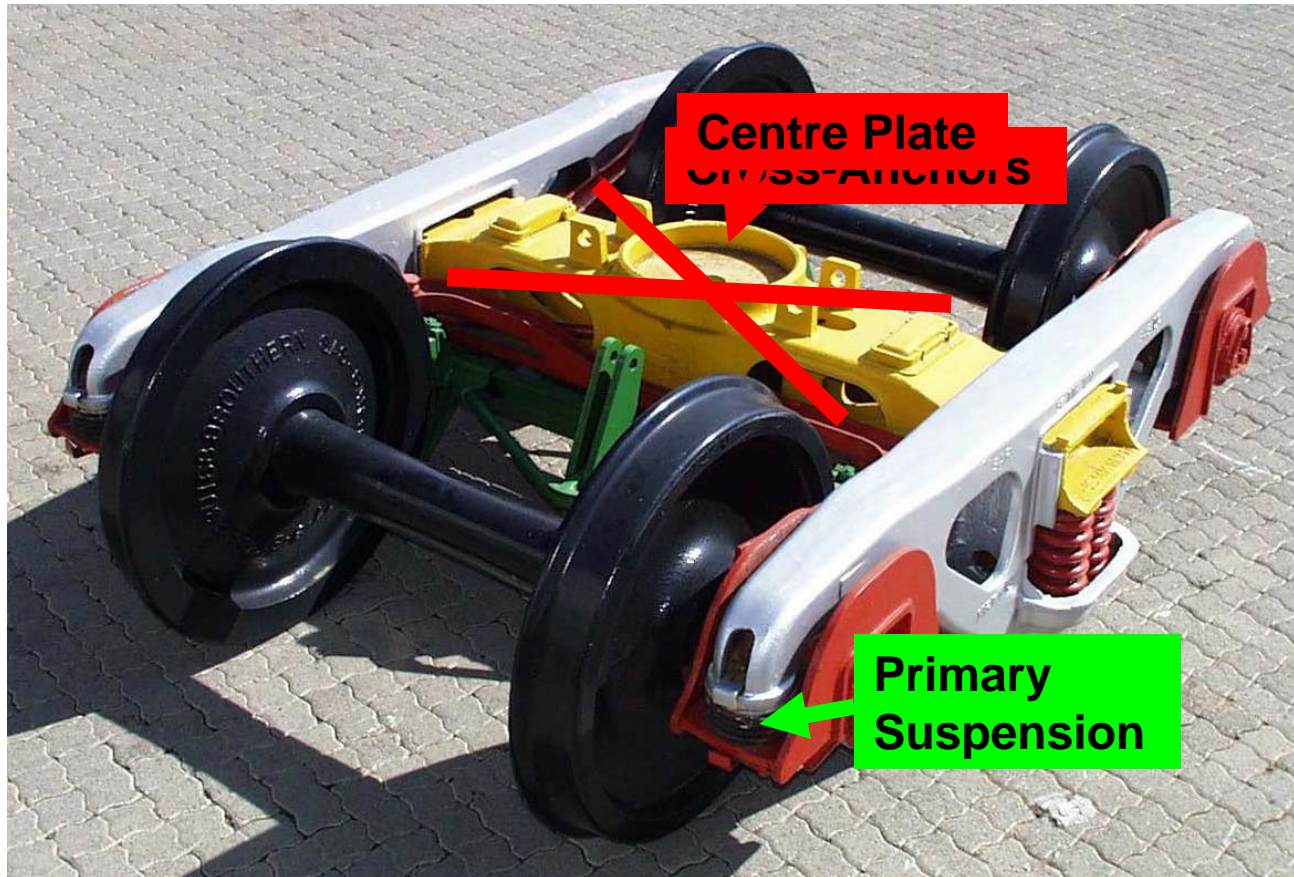
- Wheel maintenance ⇒ High cost component
- Technical interventions to reduce wheel tread and wheel flange wear rates should continuously be investigated
- Research project:
 - Investigate the possibility to further reduce wheel wear by optimising the lateral and longitudinal primary suspension stiffness and centre plate friction of self-steering three-piece bogies

BOGIE DEVELOPMENT

- **1779: First known proposal of a bogie**
- **1829: Importance of bogie alignment in curves highlighted**
- **1832: First locomotive with a swivelling leading bogie**
- **1850's:**
 - **Restrained bogie yaw by centre plate friction:**
 - **Improved bogie curving performance and acceptable stability**
 - **Three-piece bogie development:**
 - **Still used today due to low life cycle cost and continuous improvements to meet new business demands (speed, axle load, ...)**

BOGIE DEVELOPMENT

- 1970's: Scheffel developed the self-steering three-piece bogie

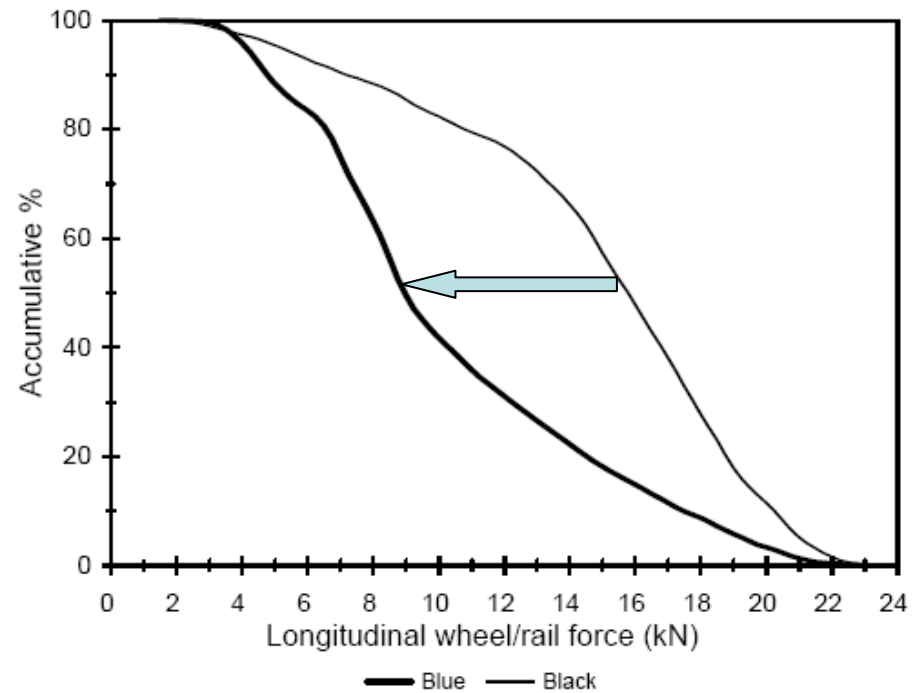
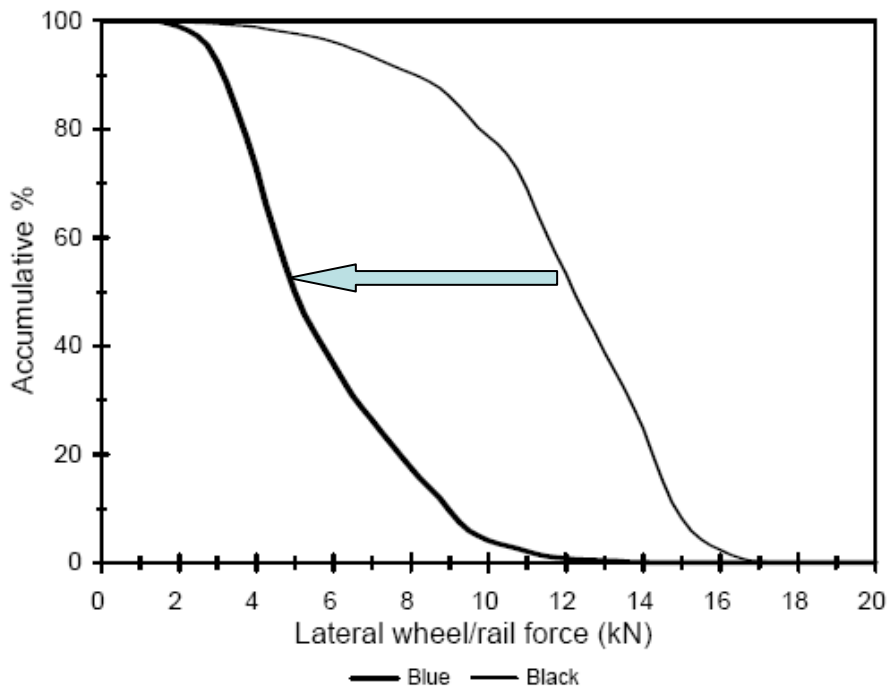


1 PROBLEM DEFINITION

- Curving performance of LKAB self-steering bogies under load:
 - **Not acceptable** due to binding at centre plate
 - Binding at centre plate compensated by significant wheelset yaw
- Solution:
 - Reduced centre liner's coefficient of friction ✓✓✓
- Influence on wheel wear due to
 - Centre plate friction / binding ???
 - Wheelset yaw = f (primary suspension) ???
- Some answers to these questions are presented in this paper
- ...

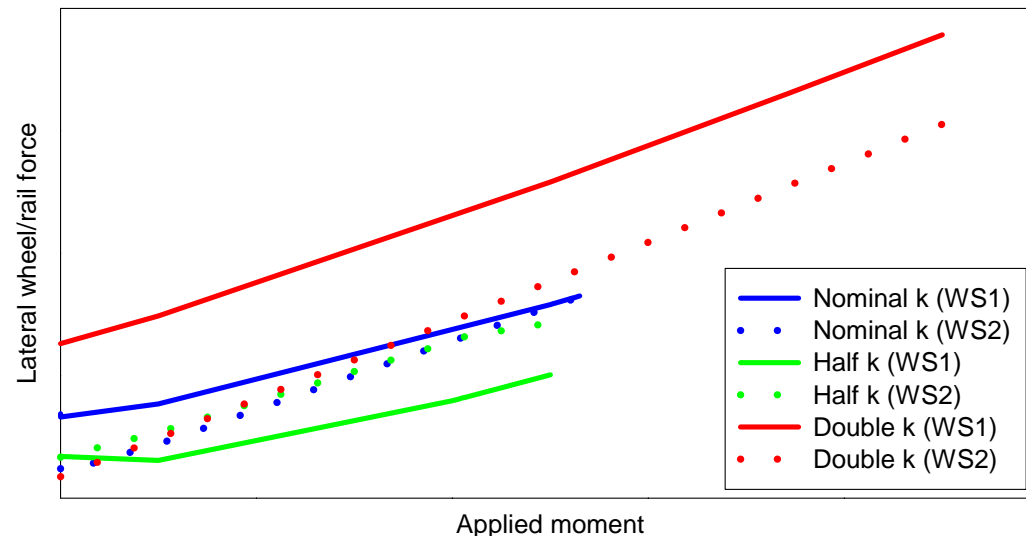
PROBLEM DEFINITION

- Tests on South African coal export line to evaluate bogie curving performance



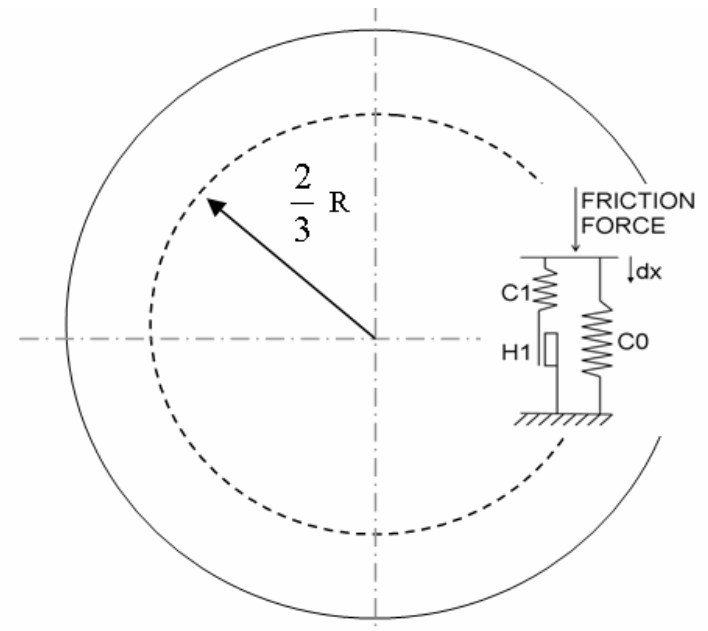
1 RUNNING DYNAMICS SIMULATION MODEL

- Linear 6 degrees of freedom model
- **Lower** longitudinal primary suspension stiffness
 - Lateral wheel-rail force ↓ at leading wheelset
 - Insignificant changes at trailing wheelset
- **Lower** lateral primary suspension stiffness
 - No significant changes



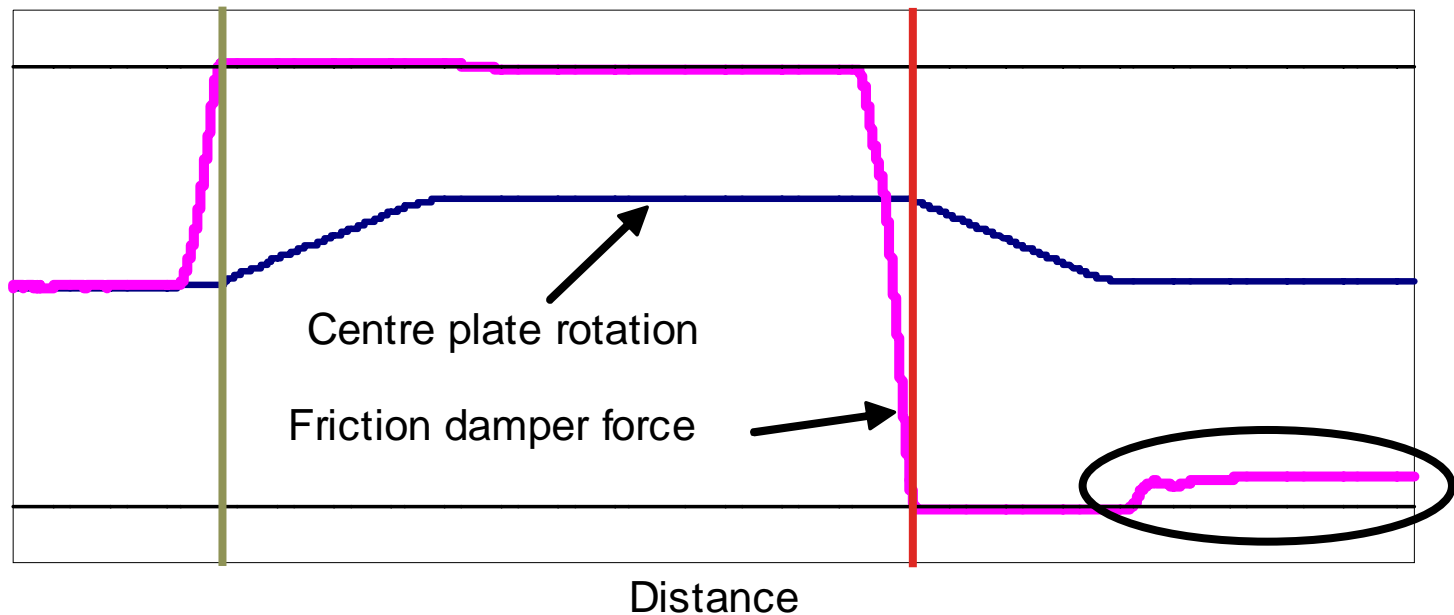
1 RUNNING DYNAMICS SIMULATION MODEL

- Non linear MSC.ADAMS/Rail model of container wagon with three-piece self-steering bogies
- Centre plate model:
 - Correct modelling of stick-slip behaviour ⇒ **critical**
 - Connection model:
 - Rotational joint
 - Bushing element
 - Linear friction damper



1 RUNNING DYNAMICS SIMULATION MODEL

- Bogie rotation through 300m curve at 70km/h
- Bogie rotation once friction damper force is exceeded
- Misalignment on straight track

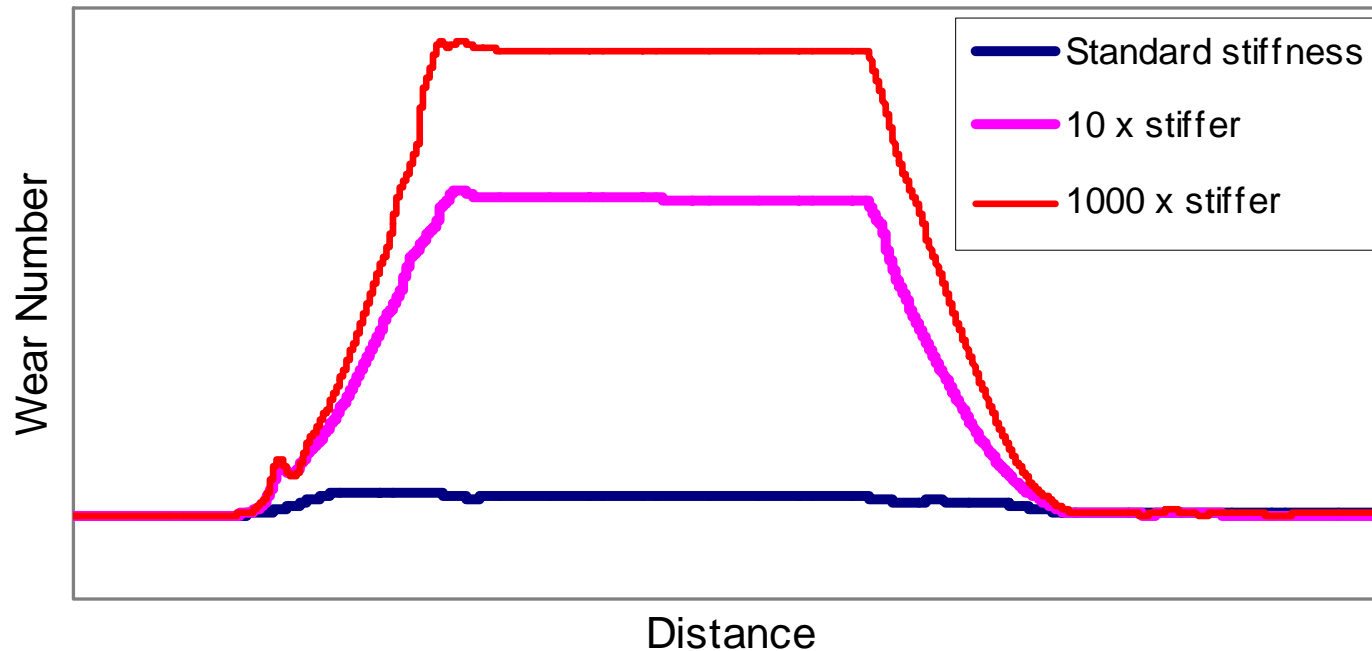


RUNNING DYNAMICS SIMULATION MODEL

- **Performance parameters:**
 - **Bogie rotation**
 - **Friction torque at centre plate**
 - **Longitudinal, lateral and spin creep forces**
 - **Equivalent longitudinal and lateral wheel/rail forces**
 - **Angle of attack**
 - **Derailment ratio**
 - **Wheel unloading**
 - **Wear number**
 - **Leading bogie high rail wheel**
 - **Sum of leading bogie wheels**

1 RUNNING DYNAMICS SIMULATION RESULTS

- **Wheel wear prediction:**
 - **Self-steering three-piece bogie <<< Standard three-piece bogie**



1 RUNNING DYNAMICS SIMULATION RESULTS

- Loaded wagon at balancing speed through a 300m curve

| Primary suspension stiffness | <u>Average bogie wheel wear number</u> | | | |
|------------------------------|--|-------------|-------------|-------------|
| | Centre plate friction | | | |
| | Free | 0.11 | 0.49 | Fixed |
| 0.5K-lat; 0.5K-long | 420 | 457 | 1061 | 1903 |
| <i>K-lat; 0.5K-long</i> | 470 | 502 | 1305 | 3902 |
| <i>0.5K-lat; K-long</i> | 1435 | 1653 | 3088 | 5127 |
| K-lat; K-long | 1562 | 1743 | 3070 | 8132 |
| <i>2.0K-lat; K-long</i> | 1817 | 1957 | 3212 | 18073 |
| <i>K-lat; 2.0K-long</i> | 4341 | 4580 | 6572 | 19915 |
| <i>2.0K-lat; 2.0K-long</i> | 4552 | 4767 | 6838 | 30909 |
| <i>10K-lat; 10K-long</i> | 14156 | 14838 | 17434 | 119852 |
| <i>1000K-lat; 1000K-long</i> | 19398 | 20048 | 23639 | 300388 |

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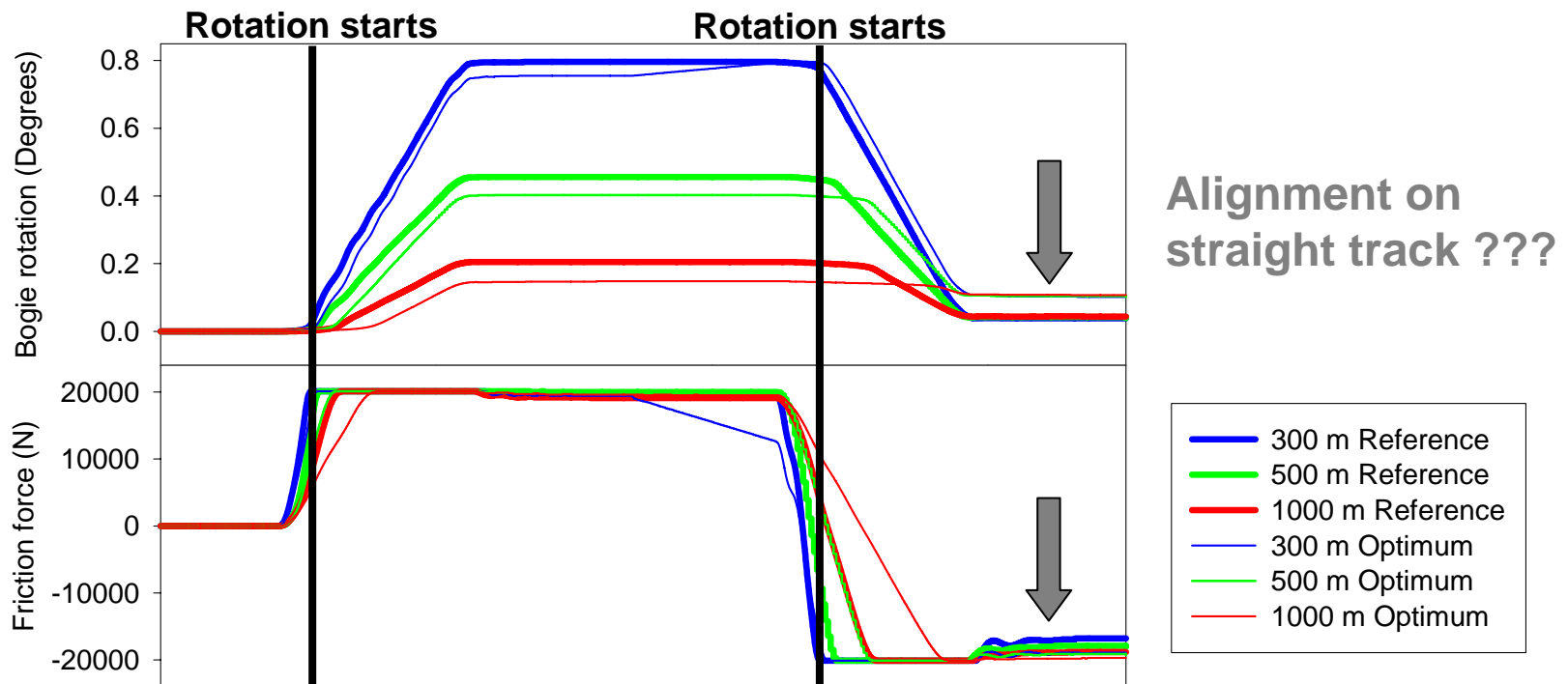
- Less wear but what about the stability speed ???

| Centre plate friction | Wear number | Stability Speed [km/h] | |
|------------------------------|-------------|------------------------|--------------|
| | | Empty | Loaded |
| 0.5K-lat; 0.5K-long | 457 | 80 | 140 ✓ |
| <i>K-lat; 0.5K-long</i> | 502 | 80 | 150 |
| <i>0.5K-lat; K-long</i> | 1653 | 90 | 160 |
| K-lat; K-long | 1743 | 90 | 160 |
| <i>2.0K-lat; K-long</i> | 1957 | 100 | 170 |
| <i>K-lat; 2.0K-long</i> | 4580 | 110 | 190 |
| <i>2.0K-lat; 2.0K-long</i> | 4767 | 110 | 210 |
| <i>10K-lat; 10K-long</i> | 14838 | 120 | > 210 |
| <i>1000K-lat; 1000K-long</i> | 20048 | 100 | 100 |

1 RUNNING DYNAMICS SIMULATION RESULTS

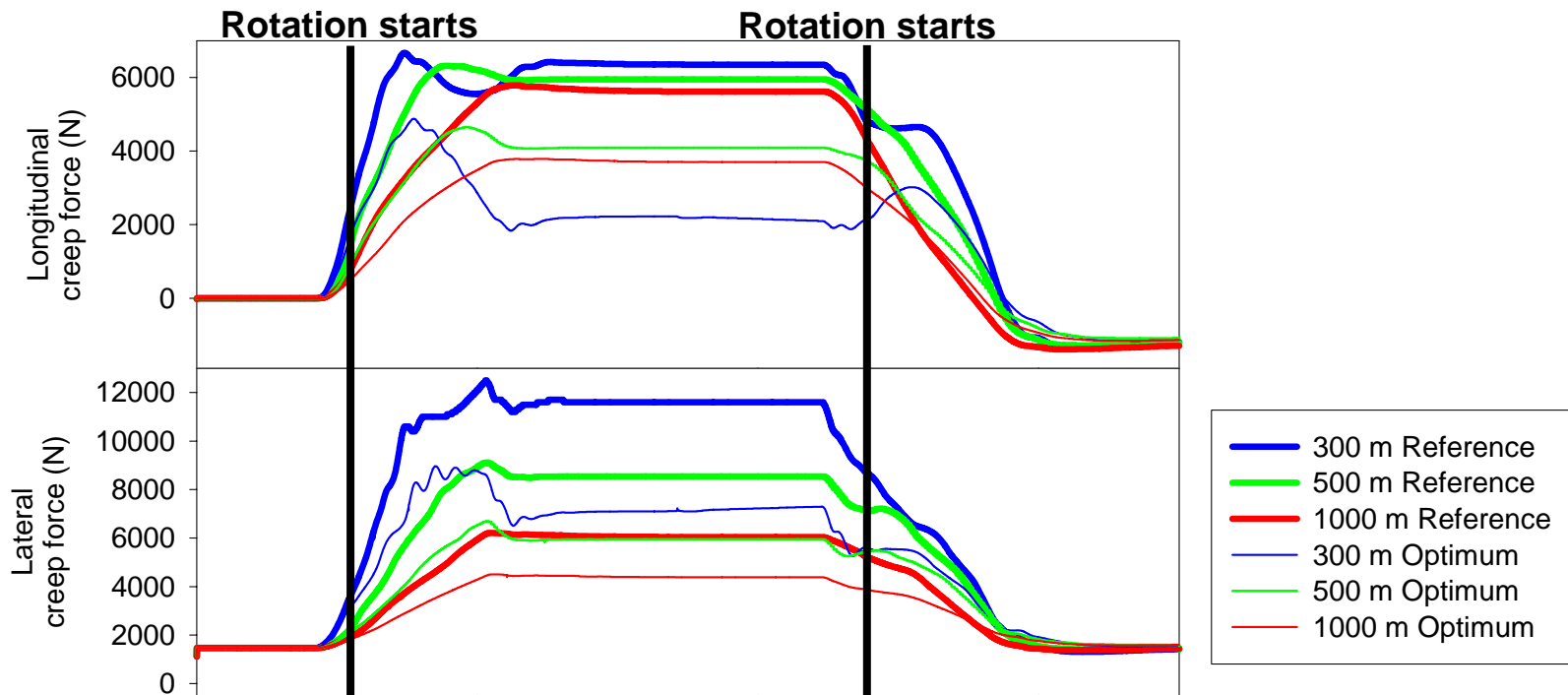
▪ Bogie rotation:

- Lower primary stiffness \Rightarrow More wheelsets yaw \Rightarrow Bogie rotation \downarrow
- Lower moment transferred from w/r interface to centre plate



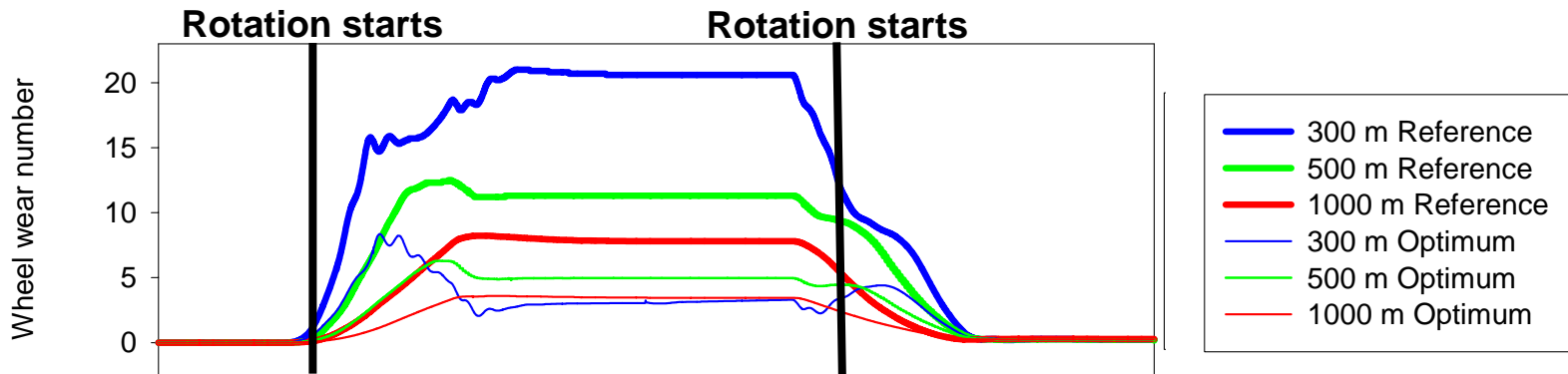
1 RUNNING DYNAMICS SIMULATION RESULTS

- Creep forces at leading high rail wheel:
- Wheel wear rate dominated by lateral creep \Rightarrow angle of attack




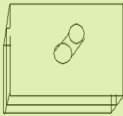


1 RUNNING DYNAMICS SIMULATION RESULTS

- Wheel wear at leading high rail wheel:



ON-TRACK TESTS

- Validate ADAMS/Rail model

| | | | | Coefficient of friction | | |
|---------------------------------|----------------------------|------------------------------------|---|-------------------------|------|-------|
| | | | | 0.11 | 0.49 | Fixed |
| Primary suspension arrangements | <i>K-lat; K-long</i> | Standard HS Mk VII rubber sandwich |  | Ref. | X | X |
| | <i>0.5K-lat; 0.5K-long</i> | Modified HS Mk V rubber sandwich |  | Opt. | X | X |
| | <i>K-lat; 2.0K-long</i> | Rubber sandwich chevron |  | X | X | X |
| | <i>2.0K-lat; K-long</i> | Rubber sandwich chevron |  | X | X | X |

CONCLUSION

- **Wheel wear:**
 - **Significantly less with lower longitudinal primary suspension stiffness**
 - **Marginally less with lower lateral primary suspension stiffness**
 - **Significantly less with lower centre plate friction**
- **Safe running speed maintained**
- **Final optimisation of lateral and longitudinal primary suspension stiffness depends on the physical load bearing capacity of the rubber suspension elements**
- **Following a model verification through on-track tests a final technical recommendation will be made**
- **Depending on a cost-benefit analysis the technical recommendation will be considered for implementation**

Thank-you

- **Questions**

